

# AOE/ESM 4084 “Engineering Design Optimization”

## Optimization of Unconstrained Problems with $N$ -Variables

- Random Search

- One of the most inefficient but easiest to implement search methods for  $N$ -dimensional optimization problems,

$$x_i = x_i^l + r(x_i^u - x_i^l)$$

- where  $x_i^l$  and  $x_i^u$  are the lower and upper bounds on the design variables, respectively, and  $r$  is a real random number between 0 and 1.0.

## • One-Dimensional Minimization

- Most n-dimensional search algorithms use one dimensional minimization to determine the minimum along a specified direction,

$$\mathbf{x} = \mathbf{x}^q + \alpha \mathbf{d}^q$$

- where  $\mathbf{x}^q$  is the current point  $\mathbf{d}^q$  is the direction vector at that point, and  $\alpha$  is the variable which determines how far one needs to move along  $\mathbf{d}^q$  to reach minimum.
- The function to be minimized,  $f(\mathbf{x})$ , can now be expressed in terms of the variable  $\alpha$ .

$$\textit{Minimize} \quad f(\mathbf{x}) = f(\mathbf{x}^q + \alpha \mathbf{d}^q) = f(\alpha)$$

$$\textit{at minimum} \quad \alpha = \alpha^*$$

- **Methods for 1-D Minimization**
  - Bracketing
  - Polynomial Approximations
  - Golden Section Search

## • Bracketing (Fig 2-11, Vanderplaats)

- We assume that the solution lies in the positive domain, and the function has a minimum.
- Initialize  $\alpha_L = 0.0$ , small  $\Delta\alpha$ ,  $a = (1+\sqrt{5})/2$  (Gold. Sect. Ratio), and  $\alpha_{max}$ .
- Compute lower and upper bound values of the interval and the function at those points:  $f_L = f(\alpha_L)$ ,  $\alpha_U = \alpha_L + \Delta\alpha$ , and  $f_U = f(\alpha_U)$
- If  $f_U > f_L$ , minimum is bracketed, exit. Other wise,
- Let  $\alpha_I = \alpha_U$  and  $f_I = f_U$ . Compute  $\alpha_U = (1+a)\alpha_I - a \alpha_L$
- If  $\alpha_U > \alpha_{max}$ , exit unbounded.
- If not, compute  $f_U = f(\alpha_U)$ .
- If  $f_U > f_I$ , minimum is bracketed, exit
- If not, let  $\alpha_L = \alpha_I$  and  $f_L = f_I$ , and go to 5th bullet to repeat the process.

## • Polynomial Approximations

- Evaluate the function to be minimized and possibly its derivatives at several points and then fit a polynomial of desired order to those points.
- Depending on the order of the polynomial, the minimum of the polynomial can easily be evaluated, and would produce a good estimate of the minimum of the actual function.
- Different possible approximations and the information needed
  - 2-Point Quadratic:  $f_1, f_2$  and either  $f'_1$  or  $f'_2$
  - 3-Point Quadratic:  $f_1, f_2$  and  $f_3$
  - 3-Point Cubic:  $f_1, f_2, f_3$ , and derivative at one of the points
  - 4-Point Cubic:  $f_1, f_2, f_3$ , and  $f_4$

## • Golden Section Search

- Assume the minimum is bracketed between  $\alpha_L$  and  $\alpha_U$ , and the function is unimodal in the interval.
- Compute 2 intermediate points:  $\alpha_1 = \alpha_L + \tau (\alpha_U - \alpha_L)$ ,  $\alpha_2 = \alpha_U - \tau (\alpha_U - \alpha_L)$   
where  $\tau = 1 - 1/a = (3 - \sqrt{5})/2$  and  $a = \text{Golden Section Ratio}$
- Either  $\alpha_1$  or  $\alpha_2$  will be the new bound on the minimum
- If  $f_1 > f_2$ , then  $\alpha_1$  forms the new lower bound, replacing  $\alpha_L$
- If  $f_2 > f_1$ , then  $\alpha_2$  forms the new upper bound, replacing  $\alpha_U$
- The remaining point will be either  $\alpha_1$  or  $\alpha_2$  depending on the case above
- A new  $\alpha_1$  or  $\alpha_2$  and associated function value will be computed by using the equations above